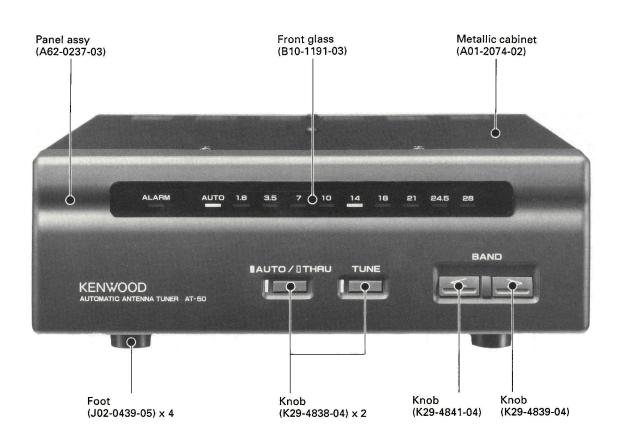
# AUTOMATIC ANTENNA TUNER AT-50 SERVICE MANUAL

KENWOOD

B51-8209-00(O)1196

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## **CIRCUIT DESCRIPTION**

#### Automatic antenna tuner

The transmission power from the transmitter is passed through the current/voltage detection transformers L1 and L2, which use a troidal core. The current and voltage components detected here are rectified by the waveform rectification circuit consisting of D3 to D5 and Q1, and D6 to D8 and Q2, and then phase compared by IC1 (SN74S74NS). The output signals from pins 8 and 9 of IC1 ( $\overline{Q}$  and Q) are passed through switch IC2 (TC4066BF) and go to motor drive IC, IC4 (BA6109U2). Variable resistor VR1 with a motor is driven to rotate variable condenser VC101 so that the phase difference of the voltage and current components decreases.

The current and voltage components detected by L1 and L2 are rectified by germanium diodes D1 and D2 (IN60) and are applied to the comparator of voltage comparison circuit IC6 (NJM2902M) as the amplitude component. The comparator output is passed through switch IC3 (TC4066BF). It then goes to another motor drive IC5 (BA6109U2), and variable resistor VR2 with a motor is driven to rotate variable condenser VC102 so that the amplitude difference decreases.

Therefore, variable condenser VC101 for capacitance adjustment is controlled so that the current and voltage phases match. Variable condenser VC102 for resistance adjustment is controlled so that the current and voltage amplitude difference decreases. The SWR is 1 when the phases match and there is no amplitude difference.

The motor speed of VR1 and VR2 is determined by the duty ratio of the pulse input to pin 8 of IC4 and IC5, and is controlled by the speed of the VSWR calculated by the CPU and the preset value.

Pulse signals SPD1 and SPD2 output from the CPU pass through Q7 and Q8 (DTC143EK), are amplified by Q5 and Q6 (2SA1204), and the resulting signals go to IC4 and IC5 as control pulses.

If the SWR is 3 or more, the motor runs at high speed since the duty cycle of the motor drive voltage pulse is 100%. If the SWR is 2, the duty cycle becomes about 50%, and the motor runs at low speed.

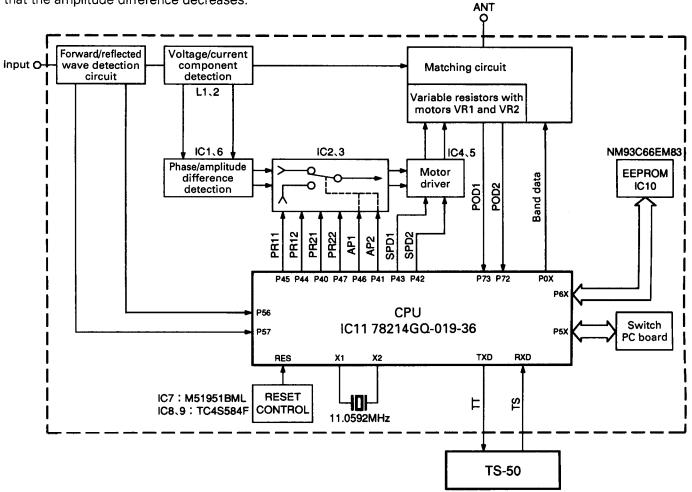


Fig.1 Block diagram

## **CIRCUIT DESCRIPTION**

The matching circuit is type T, and the tap position from 1.8 to 30 MHz is switched by seven relays K102 to K108.

Variable resistors VR101 and VR102 with motors are linked to the rotation axes of variable condensers VC101 and VC102 with couplings. The position detection voltages of POD1 and POD2 (0 to 5 V) are generated according to the capacitance of the variable condensers. This position data is input to the CPU via the analog-to-digital converter, and is used as the reference voltage in the feedback control system for preset tuning. It is also used for preset data and end detection.

Since the variable resistors with motors used here are not endless and the rotation angle is limited, the AT-50 limits the rotation range from the minimum to the maximum capacitance of the variable condenser plus an allowance.

The microcomputer monitors POD1 and POD2 to effect this control, like the reset tuning that will be described later. If the lower limit voltage of 0.8 V or the upper limit voltage of 4.0 V is reached, the microcomputer detects that the voltage is close to one limit. AP1 and AP2 are made high to return the voltage to the other limit. If the variable capacitor is VC101, and the voltage is close to the lower limit with respect to PRE1, the voltage near the upper limit is output. If the voltage is close to the upper limit with respect to PRE1, the voltage near the lower limit is output.

The other variable condenser VC102 is fixed. If the voltage for one variable condenser exceeds the limit, it is returned to the other limit. The other variable condenser remains in the same position.

The logic of PR11 to PR22 is the same as that of IC4 and IC5, and the signal output from the CPU passes through IC2 and IC3, and goes to IC4 and IC5.

The band LEDs on the panel indicate the band and SWR. They show the SWR only during tuning; otherwise, they show the band.

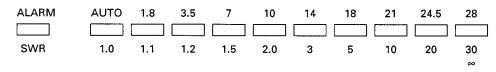


Fig.2 LED Display

#### Local tuning mode

When the AUTO/THRU switch is set to AUTO, pin 3 of IC11 goes high, Q16 is turned on, the AUTO/THRU switching relay K101 closes, and AT is inserted to prepare for tuning. If variable condensers VC101 and VC102 are not at the preset position of that band, they are set to the preset position, and the AT TUNE operation starts after presetting is complete. Pin 3 of IC11 goes low and in THRU mode during presetting.

When AT TUNE is turned on in this condition, the unit waits for tuning. If CW transmission power of about 10 W is transmitted, AP1 and AP2 go high, the motor is no longer controlled by the microcomputer, but controlled in analog form, and tuning starts.

Analog control is used during tuning, except that the reverse operation ends after end detection. If the VSWR is less than 1.2, ATS goes high and Q10 turns on. If the VSWR falls below 1.2, tuning is regarded as completed, and the AT TUNE operation is terminated.

#### Semi-automatic tuning mode

When the AUTO/THRU switch is set to AUTO and the band LED is set to AUTO with the UP and DOWN keys, semi-automatic tuning mode is entered. If the microcomputer in HALT mode receives a transmission signal, the VSF on the detection circuit goes high, Q19 is turned on, and the microcomputer exits the HALT mode and starts semi-automatic tuning.

## **CIRCUIT DESCRIPTION**

#### Automatic tuning mode

If the TS-50 is connected to the AT-50 with the special relay cable (supplied with the AT-50), the TS-50 checks whether the AT-50 is connected by the TT and TS lines when it is turned on. The AT-50 enters automatic tuning mode when it receives an AT connection command from the transceiver. If the AT-50 is turned on after the TS-50, the AT-50 connection is not checked, and the AT-50 does not enter automatic tuning mode.

The TS-50 performs all operations in automatic tuning mode. When the AT TUNE key on the TS-50 is pressed, "AT" lights on the LCD. The AUTO/THRU LED on the AT-50 shows AUTO. Pin 3 of IC11 goes high, Q16 is turned on, AT is inserted, and tuning starts. If variable condensers VC101 and VC102 are not at the preset position for that band, they are set to the preset position, and the AT TUNE operation and TS-50 transmission start after presetting is complete. Pin 3 of IC11 goes low and in THRU mode during presetting.

#### • Preset tuning mode

When automatic, semi-automatic, or local tuning ends, the microcomputer stores the position of the variable condenser in memory as preset data for that band.

If the band is changed after tuning in another band, APRE goes high, and the microcomputer controls the motor and performs preset tuning.

The initial preset data when the microcomputer is reset is the standard data when tuning is performed with a  $50\Omega$  load in each band.

#### HALT mode

When the microcomputer is in HALT mode, the CPU stops to prevent the microcomputer noise from being received.

The microcomputer exits HALT mode in the follow-ing cases:

- During transmission
- During presetting (The AUTO/THRU relay is in THRU mode.)
- While the AUTO/THRU, AT TUNE, UP, or DOWN switch is being held down
- When it waits for tuning in local tuning mode. (The AUTO/THRU relay is in THRU mode.)

The microcomputer is in HALT mode in all other cases.

#### Setting the extended functions

The following functions can be set by installing or removing jumper resistors (W23 to W27):

#### SWR display

	*YES	NO
W23	0	×

Baud rate

	*4800	9600
W24	0	X
* 1.***1		0 -

### **Digital Control Circuit**

#### Digital control

The A-50 digital section contains a CPU (78 214GQ-019-36) and an EEPROM (NM93C66EM83). This circuit controls various other circuits. The reset IC is an M51951BML. When the power supply voltage is dropped, backup data is written into the EEPROM, and when the power is switched on, backup data is read from the EEPROM into the CPU.

#### System reset and backup

The power supply voltage (5-V line) is always monitored by IC7 (M51951BML) and the power supply voltage (14-V line) is always monitored by IC14 (M51951BML) to prevent destruction of data in memory by the power being switched on or off, or momentary power failure.

If the line voltage is low, IC7 outputs a reset signal and and IC14 outputs a non-maskable interrupt request (NMI) to the CPU. If a signal is input to the NMI pin for 10 $\mu$ s or more, the IC detects a valid edge, and outputs backup data to the EEPROM (IC10).

When the power supply voltage becomes normal (including power-on), the CPU and I/O are initialized and operation resumes after the time constant set by R51 and C51.

## **CIRCUIT DESCRIPTION**

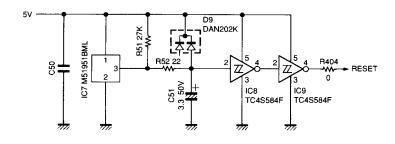


Fig. 3 System reset circuit

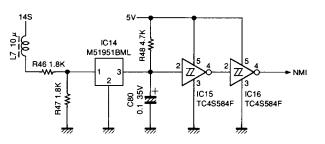


Fig. 4 System backup circuit

#### Motor control signal and variable condenser A/ D value read

The CPU makes AD1 (P46) and AP2 (P41) high to change motor control from analog to the microcomputer during inversion when tuning or presetting.

The motor speed after the variable condenser moves until it stops is controlled by changing the high and low duty ratios with SPD1 (43 pins) and SPD2 (42 pins). When the stop position is approached during presetting or when the SWR falls during tuning, the motor speed decreases. When the SWR becomes 1.2, the motor stops. The rotational direction of the motor during presetting is controlled by PR11 (P45), PR12 (P44) and PR21 (P40), and PR (P47). (See Table 1.)

		PR11	PR12	PR21	PR22
Motor 1	Normal rotation	Н	L		
	Reverse rotation	L	н		
	Stop	L	L		
Motor 2	Normal rotation			Н	L
	Reverse rotation			L	н
	Stop			L	L

Table 1 Direction of rotation of motors 1 and 2

#### Serial interface

The CPU has an asynchronous serial interface (TTL level) to transfer data to and from the TS-50. (Auto mode) Data format is one start bit, 8 data bits, and two stop bits; transmission speed is 4800bps. The control signal from the TS-50 is received through RXD (pin 44) and the answerback signal is sent to the TS-50 through TXD (pin 45).

#### EEPROM access

Since the CPU does not back up data, backup data is stored in IC10 (NM93C66EM83). If there is an input to the NMI pin when the power supply voltage is dropped, the CPU outputs backup data to IC10 CS (pin 1). When the power is turned on and the CPU receives a reset signal for the generation stabilizing time (about 40 ms), the previous backup data is read from the EEPROM.

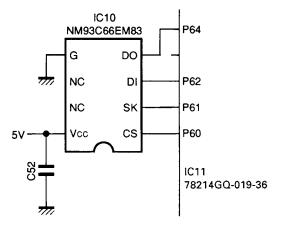


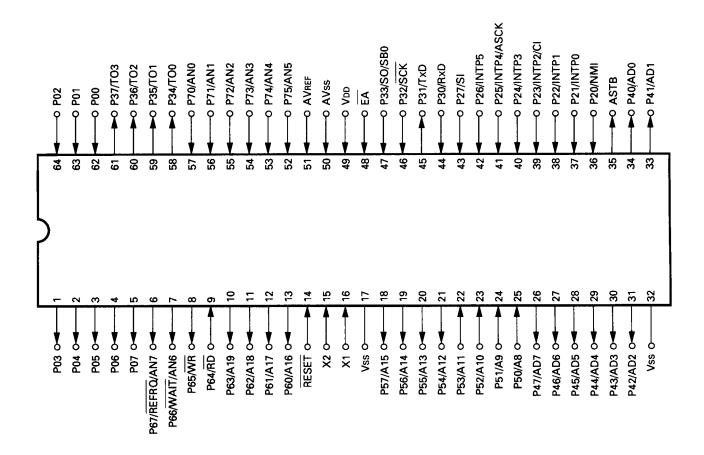
Fig. 5 EEPROM circuit

**AT-50** 

## **SEMICONDUCTOR DATA**

#### CPU: 78214GQ-019-36 (IC11)

Terminal connection diagram



#### Terminal function

Pin No.	Pin name	Signal name	1/0	Function	Active condition	H/L
1	P03	7A	0	7MHz band relay signal.	When 7MHz band is selected.	Н
2	P04	4A	0	3.5MHz band relay signal.	When 3.5MHz band is selected.	н
3	P05	ATA	0	Through relay signal.	When AT is inserted.	н
4	P06	28A	0	28MHz band relay signal.	When 28MHz band is selected.	н
5	P07	25A	0	24.5MHz band relay signal.	When 24.5MHz band is selected.	н
6	P67		0			
7	P66		0			
8	P65		0			
9	P64	EDI	I	EEPROM data input.		
10	P63		0			
11	P62	EDO	0	EEPROM serial data.		
12	P61	ESK	0	EEPROM serial clock.		
13	P60	ECS	0	EEPROM chip select.	When EEPROM is accessed.	Н
14	RESET	RES	Ι	CPU reset input.	When reset.	L
15	X2	X2	I	Crystal oscillator connection pin.	11.0592MHz.	_

## **SEMICONDUCTOR DATA**

Pin No.	Pin name	Signal name	I/O	Function	Active condition	H/L
16	X1	X1	ł	Crystal oscillator connection pin.	L77-1380-05.	—
17	Vss	Vss	_	Ground voltage.		
18	P57	SAT	0	AT IN key switch input.	When AT IN key is pressed.	L
19	P56	STN	0	TUNE key switch input.	When TUNE key is pressed.	L
20	P55	SDN	0	DOWN key switch input.	When DOWN key is pressed.	
21	P54	SUP	0	UP key switch input.	When UP key is pressed.	L
22	P53	LCK		LED driver serial clock.		
23	P52	LDA	l	LED driver serial data.		
24	P51	LBL	-	LED driver light control output.	When LED lights.	н
25	P50	LEN		LED driver enable.	Data enable.	н
26	P47	PR22	0	Preset control output.		
27	P46	AP1	0	Tuning/preset switching.	Preset.	н
28	P45	PR11	0	Preset control output.		
29	P44	PR12	0	Preset control output.		
30	P43	SPD1	0	Speed control output 1.	When the motor runs.	н
31	P42	SPD2	0	Speed control output 2.	When the motor runs.	——————————————————————————————————————
32	Vss	Vss	_		When the motor runs.	
33	P41	AP2	0	Tuning/preset switching.	Preset.	
34	P40	PR21	0	Preset control output.		
35	ASTB	11121	0			
36	NMI	NMI		12 OV normalization data interest in the		<u> </u>
30	P21	INTPO	1	13.8V power supply voltage drop interrupt input.	When the voltage drops.	
37			-			
	P22	INTP1	ŀ			L
39	P23				· · · · · · · · · · · · · · · · · · ·	
40	P24	0.01				
41	P25	OP1		Stop switch input (SWR display).	Jumper W23 is installed.	L
42	P26	0.50	<u> </u>			
43	P27	OP2	<u> </u>	Stop switch input (baud rate).	Jumper W24 is installed.	L
44	RXD	RXD		Serial control input.		
45	TXD	TXD	0	Serial output.		
46	P32		!			
47	P33		I			
48	EA	EA		ROMIess instruction.	When the internal ROM is used.	H
49	Vdd	Vdd		Power input.	+5V input.	
50	AVss	AVss	I	Analog-to-digital converter reference potential.	Analog ground potential.	-
51	AVREF	AVREF	1	Analog-to-digital converter reference voltage.	Full-scale voltage.	
52	P75		1	GND.		
53	P74		l	GND.		
54	P73	POD1	ł	Variable condenser A position voltage.	Analog input.	
55	P72	POD2		Variable condenser B position voltage.	Analog input.	
56	P71	VF	ł	Forward wave voltage.	Analog input.	
57	P70	VR	I	Reflected wave voltage.	Analog input.	
58	P34	OP3	0			
59	P35	OP4	0			
60	P36	OP5	0			
61	P37		0		· · · · · · · · · · · · · · · · · · ·	
62	P00	18A	I	18MHz band relay signal.	When 18MHz band is selected.	н
63	P01	14A	I	14MHz band relay signal.	When 14MHz band is selected.	Н
64	P02	10A	ł	10MHz band relay signal.	When 10MHz band is selected.	H

## **DESCRIPTION OF COMPONENTS**

#### AT UNIT (X53-3470-00)

Ref. No.	Use/Function	Operation/Condition/Compatibility
IC1	D-FF	Phase difference detection.
IC2	Analog switch	Control switching VR1.
IC3	Analog switch	Control switching VR2.
IC4	Motor drive	For VR1.
IC5	Motor drive	For VR2.
IC6	Comparator	Amplitude difference detection.
IC7	System reset	Reset signal generation.
IC8,9	Inverter	Reset signal waveform rectification.
IC10	EEPROM	Band and preset position data memory.
IC11	CPU	8-bit microcomputer.
IC12	Regulator	14V→8V
IC13	Regulator	14V→5V
IC14	System backup	Backup signal generation.
IC15,16	Inverter	Backup signal waveform rectification.
IC201,202	LED switch	Serial-to-parallel conversion.
Q1,2	Amplification	Waveform rectification.
Q3,4	Switching	On when AP is high.
Q5~Q8	Switching	Motor speed control pulse.
D1	Detection	Current amplitude detection.
D2	Detection	Voltage amplitude detection.
D3~D8	Switching	Clipper.
D9	Charging diode	Reset voltage discharging.
D10,11	Protection diode	Analog-to-digital converter input port protection.
D13,14	Switching	HALF mode termination.
D101	High-frequency rectification	Reflected wave rectification.
D102	High-frequency rectification	Forward wave rectification.
D103~D110	Switching	Spike absorption.
D111	Lightning surge protection	
D112	Protection against reverse connection	For power terminal.
D113	Surge absorption	Power line protection.
D201~D213	LED	Display LED (band, switch).
D301	Reverse flow prevention	
D302	Reference voltage	18V.
D303	Protection	Shorts the 14V line to blow the fuse if overvoltage occurs.

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AT-50

## PARTS LIST

× New Parts

#### Parts without Parts No. are not supplied

Les articles non mentionnes dans le Parts No. ne sont pas fournis.

Teile ohne Parts No. werden nicht geliefert.

Address New Parts No. Ref. No. Description Desti-Re-Darte nation marks 参照番号 晋 部品番号 位 新 部 品名/規格 # 向 備考 AT-50 1 A \* A01-2074-02 METALLIC CABINET(TOP) 2 A01-2075-02 3B \* METALLIC CABINET(BOTTOM) 3 24 A10-1332-02 CHASSIS \* (MAIN) 4 ЗA \* A62-0237-03 PANAL ASSY 5 ЗA B10-1191-03 FRONT GLASS \* 6 7 S/NO LABEL(ITEM CARTON BOX) 3C B42-2454-04 LABEL(M4×8MAX) 1 A B42-2455-04 8 1 B B42-3343-04 S/NO LABEL(BODY) 9 B42-3395-04 LABEL(FCC) 1 B К 10 3C \* B42-4528-04 LABEL(GREEN POINT MARK) M,E WARRNTY CARD 1 D B46-0419-00 11 E B46-0430-00 WARRNTY CARD 11 1 D Κ 12 1 D \* B62-0320-00 INSTRUCTION MANUAL 13 B72-0521-04 MODEL NAME PLATE 1 B \* 14 2B \* C02-0025-05 VARIABLE CONDENSER(MAX 300PF) 15 2B D22-0402-05 JOINT(COUPLING) 16 18 E04-0167-05 RF COAXIAL CABLE RECEPTACLE 17 2B E23-0677-04 TERMINAL(GND) E30-3145-05 18 1 D \* TRUNK CABLE (ACSY) 19 1 D \* E30-3155-05 CONVERSION CABLE (ACSY) E37-0316-05 \* CONNECTING WIRE \* E37-0317-05 CONNECTING WIRE (3P) \_ E37-0318-05 CONNECTING WIRE \* (12P) E37-0374-05 CONNECTING WIRE \* 24 1 D F06-4029-05 FUSE (4A:ACSY) 25 2B G02-0574-04 FLAT SPRING G13-1389-04 CUSHION (KNOB) 2A \* 2D \* H10-2765-02 POLYSTYRENE FOAMED FIXTURE(F) H10-2766-02 10 POLYSTYRENE FOAMED FIXTURE(R) \* 1 D H25-0112-04 BAG (180x250) 30 2C H25-0194-04 BAG (280×400) 3C \* H52-0385-04 ITEM CARTON BOX H62-0337-04 \* OUTER PACKING CASE 33 3A,3B J02-0439-05 FOOT 34 2B\* J21-4417-04 MOUNTING HARDWARE (VC) J61-0307-05 WIRE BAND K29-4838-04 36 3A \* KNOB (A/T,TUNE) ЗA \* K29-4839-04 KNOB (BAND: > ) 38 K29-4841-04 3A \* KNOB (BAND: < ) 1**B** N15-1040-46 FLAT WASHER (GND) N09-0641-05 SCREW(VARIABLE CONDENSER) 2B 1**A,3A** N33-2606-45 OVAL HEAD MACHIN SCREW(CASE) 1 B N35-4010-46 BINDING HEAD MACHINE SCREW(GND N87-2606-46 2A,2B BRAZIER HEAD TAPTITE SCREW(PCB 1 B N87-3008-46 BRAZIER HEAD TAPTITE SCREW 40 2A,2B X53-3470-00 \* AT UNIT (A, B, C, D/4)

L:Scandinavia Y:PX(Far East, Hawaii)

Y:AAFES(Europe)

26

27

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A

B

С

D

Е

P:Canada E:Europe

X:Australia M:Other Areas

K:USA

T:England

## **PARTS LIST**

× New Parts

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Teile ohne Parts No. werden nicht geliefert.

AT UNIT (X53-3470-00)

Ref. No.	Address	New Parts	Parts No.	D	escription			Re- mark
参照番号	位置	新	部品番号	部品	名/規	格		備考
		-	AT UNIT	(X53-3470-00)				
C1 -7 C8 ,9 C10 C11 C12 -17			CK73FB1E103K CK73FB1H102K CK73FB1E103K CE04EW1A470M CK73FB1E103K	CHIP C CHIP C CHIP C ELECTRO CHIP C	0.01UF 1000PF 0.01UF 47UF 0.01UF	K K 10WV K		
C18 C19 -21 C22 C23 C24			CK73EF1E474Z CK73FB1E103K CE04EW1A101M CK73FB1E103K CK73EF1E474Z	CHIP C CHIP C ELECTRO CHIP C CHIP C	0.47UF 0.01UF 100UF 0.01UF 0.47UF	Z K 10WV K Z		
C25 -27 C28 C30 C31 C32			CK73FB1E103K CE04EW1A101M CK73FF1E104Z CK73FB1E103K CE04EW1E470M	CHIP C ELECTRO CHIP C CHIP C ELECTRO	0.01UF 100UF 0.1UF 0.01UF 47UF	K 10WV Z K 25WV		
C 33 C 34 C 35 C 36 C 37			CK73FB1E104K CE04EW1A101M CK73FB1E104K CE04EW1E470M CK73FB1E104K	CHIP C ELECTRO CHIP C ELECTRO CHIP C	0.10UF 100UF 0.10UF 47UF 0.10UF	K 10WV K 25WV K		
C38 C39 C40 -42 C43 ,44 C45 -50			CE04EW1A221M CK73FB1E104K CK73FB1E103K CK73FB1H102K CK73FB1E103K	ELECTRO CHIP C CHIP C CHIP C CHIP C CHIP C	220UF 0.10UF 0.01UF 1000PF 0.01UF	10WV K K K K		
C51 C52 C53 ,54 C55 -59 C60			CE04EW1H3R3M CK73FB1E103K CC73FCH1H100D CK73FB1E103K CE04EW1A221M	ELECTRO CHIP C CHIP C CHIP C ELECTRO	3.3UF 0.01UF 10PF 0.01UF 220UF	50WV K D K 10WV		
C63 -66 C68 C69 -77 C78 ,79 C80			CK73FB1E103K CK73FB1E103K CK73FB1H102K CK73FB1E103K C92-0001-05	CHIP C CHIP C CHIP C CHIP C CHIP TAN	0.01UF 0.01UF 1000PF 0.01UF 0.1UF	К К К 35 W V		
C81 C82,83 C101 C102 C103			CK73FF1H473Z CE04EW1HOR1M CC45CH2H030C CC73FSL1H101J CC73FSL1H560J	CHIP C ELECTRO CERAMIC CHIP C CHIP C	0.047UF 0.1UF 3PF 100PF 56PF	Z 50WV C J J		
C104,105 C106 C107 C108-123 C124			CK73FF1H473Z CC45SL2H820J CK73FB1E103K CK73FB1E103K CK73FB1E103K CK73EF1H104Z	CHIP C CERAMIC CHIP C CHIP C CHIP C	0.047UF 82PF 0.01UF 0.01UF 0.1UF	Z J K K Z		
C201-204 C205 C206,207 C301 C302			CK73FB1H102K CE04NW1A470M CK73FB1E103K CE04EW1A221M CK73FB1E103K	CHIP C ELECTRO CHIP C ELECTRO CHIP C	1000PF 47UF 0.01UF 220UF 0.01UF	K 1 OWV K 1 OWV K		
			C05-0031-15 C05-0030-15	TRIM CAP TRIM CAP		10PF 20PF	-	

Y:AAFES(Europe)

E:Europe X:Australia M:Other Areas

A indicates safety critical components.

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Ref. No.	Address	New Parts	Parts No.	Description	Re- mark
参照番号	位置	Parts 新	部品番号	部品名/規格	備利
CN1 ,2 CN3 CN4 CN5 CN6			E04-0154-05 E40-3247-05 E40-3254-05 E40-3255-05 E40-3237-05	RF COAXIAL CABLE RECEPTACLE PIN ASSY (3P) PIN ASSY (10P) PIN ASSY (11P) PIN ASSY (2P)	
CN7 CN101,102 CN103 CN104 CN105			E40-3246-05 E04-0154-05 E40-3247-05 E40-3256-05 E23-0401-05	PIN ASSY (2P) RF CQAXIAL CABLE RECEPTACLE PIN ASSY (3P) PIN ASSY (12P) TERMINAL (TEST)	
W22 W105 W201 W301	1 B	* * *	E37-0371-05 E37-0370-15 E37-0369-15 E37-0372-05	CONNECTING WIRE CONNECTING WIRE CONNECTING WIRE CONNECTING WIRE	
F101	2B		F06-4029-05	FUSE (4A)	
A101,102			J13-0075-05	FUSE HOLDER	
L1 L2 L3 -6 L7 L8 ,9			L39-0496-05 L39-0415-25 L40-1011-12 L40-1001-12 L40-1001-48	TROIDAL COIL TROIDAL COIL SMALL FIXED INDUCTOR(100UH) SMALL FIXED INDUCTOR(10UH) SMALL FIXED INDUCTOR(10UH)	
L10 -17 L101 L102 L103 L104			L40-1011-48 L40-2221-33 L39-0480-15 L40-2221-33 L34-1276-05	SMALL FIXED INDUCTOR(100UH) SMALL FIXED INDUCTOR(2.2MH) TROIDAL COIL SMALL FIXED INDUCTOR(2.2MH) COIL	
L105 L106 L107 L108-116 X1		*	L39-1242-05 L39-0495-05 L39-0494-15 L40-1011-15 L77-1380-05	TROIDAL COIL TROIDAL COIL TROIDAL COIL SMALL COIL CRYSTAL RESONATOR(11.0592MHz)	
R1 ,2 R3 R4 R5 R6 -9			RD14BB2E101J RD14BB2E470J RK73FB2A102J RK73FB2A181J RK73FB2A181J RK73FB2A103J	RD 100 J 1/4W   RD 47 J 1/4W   CHIP R 1.0K J 1/10W   CHIP R 180 J 1/10W   CHIP R 10K J 1/10W	
R10 ,11 R12 ,13 R14 R15 R16			RK73FB2A330J RK73FB2A103J RK73FB2A181J RK73FB2A563J RK73FB2A121J	CHIP R 33 J 1/10W   CHIP R 10K J 1/10W   CHIP R 180 J 1/10W   CHIP R 56K J 1/10W   CHIP R 120 J 1/10W	
R17 R18 R19 R20 R21 -23			RK73FB2A101J RK73FB2A121J RK73FB2A563J RK73FB2A563J RK73FB2A101J RK73FB2A103J	CHIP R 100 J 1/10W   CHIP R 120 J 1/10W   CHIP R 56K J 1/10W   CHIP R 100 J 1/10W   CHIP R 100 J 1/10W   CHIP R 10K J 1/10W	
R24 R25 R26 R27 R28			RK73FB2A472J RK73FB2A103J RK73FB2A472J RD14BB2E100J RK73FB2A103J	CHIP R 4.7K J 1/10W   CHIP R 10K J 1/10W   CHIP R 4.7K J 1/10W   CHIP R 4.7K J 1/10W   RD 10 J 1/4W   CHIP R 10K J 1/10W	
R29 R30			RK73FB2A472J RK73FB2A103J	CHIP R 4.7K J 1/10W CHIP R 10K J 1/10W	

Y:PX(Far East, Hawaii) Y:AAFES(Europe)

E:Europe X:Australia M:Other Areas

T:England

▲ indicates safety critical components.

## **PARTS LIST**

× New Parts

Parts without Parts No. are not supplied.

Les articles non mentionnes dans le Parts No. ne sont pas fournis.

Teile ohne Parts No. werden nicht geliefert.

AT UNIT (X53-3470-00)

~

Ref. No.	Add	iress		Parts No.	De	scription			Desti- nation	Re-
参照番	号位	置	Parts 新	部品番号	部品	名/規	格			備考
R31 R32 R33 R34 R35				RD14BB2E100J RK73FB2A103J RK73FB2A472J RK73FB2A472J RK73FB2A103J RD14BB2E471J	RD CHIP R CHIP R CHIP R RD	10 10K 4.7K 10K 470	J J J J	1/4W 1/10W 1/10W 1/10W 1/4W		
R36 R37 ,38 R39 ,40 R41 ,42 R46 ,47				RK73FB2A101J RK73FB2A473J RK73FB2A104J RK73FB2A100J RK73FB2A100J RK73FB2A182J	CHIP R CHIP R CHIP R CHIP R CHIP R	100 47K 100K 10 1.8K	] J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R48 R49 ,50 R51 R52 R53				RK73FB2A472J RK73FB2A101J RK73FB2A273J RK73FB2A220J RK73FB2A220J RK73FB2A223J	CHIP R CHIP R CHIP R CHIP R CHIP R	<b>4</b> .7K 100 27K 22 22K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R54 -58 R59 -62 R63 -66 R67 -74 R77 -85				RK73FB2A103J RK73FB2A104J RK73EB2B101J RK73FB2A101J RK73FB2A101J RK73FB2A103J	CHIP R CHIP R CHIP R CHIP R CHIP R	1 OK 1 OOK 1 OO 1 OO 1 OK	1 1 1 1	1/10W 1/10W 1/8W 1/10W 1/10W		-
R88 ,89 R90 R101 R102-10 R106-10				RK73FB2A103J RK73FB2A334J RK73FB2A100J RK73FB2A330J RK73FB2A330J RK73FB2A270J	CHIP R CHIP R CHIP R CHIP R CHIP R	10K 330K 10 33 27	J J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R201-20 R209,21 R211-21 R214 R215-22	0 3			RK73FB2A101J RK73FB2A271J RK73FB2A391J RK73FB2A391J RK73FB2A271J RK73FB2A391J	CHIP R CHIP R CHIP R CHIP R CHIP R	100 270 390 270 390	] J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R222 R223 R224-22 R301 R302	7			RK73FB2A103J R92-0670-05 R92-0679-05 RK73FB2A470J RK73FB2A123J	CHIP R CHIP R CHIP R CHIP R CHIP R	10K 0 0HM 0 0HM 47 12K	] J	1/10W 1/10W 1/10W		
R303 R304 R305,30 R307 R401-41				RK73FB2A223J RK73EB2B222J RS14DB3A181J RS14DB3A100J R92-0670-05	CHIP R CHIP R FL-PR00F RS FL-PR00F RS CHIP R	22K 2.2K 180 10 0 0HM	J J J	1/10W 1/8W 1W 1W		
R426-44 VR1 ,2 VR3 ,4 VR101 W23 -27	24	,2B		R92-0679-05 R10-3402-05 R12-6744-05 R12-6730-05 R92-0150-05	CHIP R POTENTIOMETE TRIM POT. TRIM POT. JUMPER REST	0 00HM R 10KB 47K 220 0 00HM				
W101-10	4			R92-0150-05	JUMPER REST	O QHM				
K101 K102-10 S201,20 S203,20	2			S51-2417-05 S76-0401-05 S70-0415-05 S70-0411-05	RELAY RELAY TACT SWITCH TACT SWITCH	(A/T,TU (BAND:		)		
D1 ,2 D3 -8 D9 D10 ,11				1N60 1SS226 DAN202K RD5.1M(B1)	DIQDE DIQRD DIQRD DIQRD DIQRD					

Y:PX(Far East, Hawaii)

Y:AAFES(Europe)

T:England E:Europe

M:Other Areas

X:Australia

 $\bigstar$  indicates safety critical components.

## **PARTS LIST**

# **AT-50**

× New Parts

#### Parts without Parts No. are not supplied.

Les articles non mentionnes dans le Parts No. ne sont pas fournis.

Teile onne Parts No. werden nicht geliefert.

#### AT UNIT (X53-3470-00) MODULE UNIT : METER (X59-3940-01)

Ref. No.	Address	New Parts	Parts No.	Description		Re-
参照香号	位置	Parts 新	部晶、香叶号	部品名/規格		mark 備考
D13,14 D101,102 D103-110 D111 D112			DAP202U 1SS101 LFB01 RA301PV6Y2(0.5) U05B	DIORD DIORD DIORD DIORD (SURGE ABSORBER) DIORD		
D113 D201 D202 D203-205 D206			ERZ-M10DK220 B30-2005-05 B30-2006-05 B30-2007-05 B30-2006-05	DIORD LED LED LED LED		
D207-213 D301 D302 D303 IC1		*	B30-2007-05 RLS73 RLZ18B SF2B41 SN74S74NS	LED DIORD DIORD THYRISTOR IC(FLIP-FLOP)		
IC2 ,3 IC4 ,5 IC6 IC7 IC8 ,9			MC14066BF BA6109U2 NJM2902M M51951BML TC4S584F	IC (or TC4066BF) IC(MOTOR DRIVER) IC(OP AMP X4) IC(SYSTEM RESET) IC(SCHMITT TRIGGER)		
IC10 IC11 IC12 IC13 IC14		*	NM93C66EM83 78214C9-019-36 UPC7808H UPC7805H M51951BML	IC(CMOS EEPROM) IC (CPU) IC(VOLTAGE REGULATOR/ +8V) IC(VOLTAGE REGULATOR/ +5V) IC(SYSTEM RESET)		
IC15,16 IC201,202 Q1 ,2 Q3 ,4 Q5 ,6			TC4S584F UPD6345GS 2SC2714(Y) DTC114EK 2SA1204(Y)	IC(SCHMITT TRIGGER) IC TRANSISTOR DIGITAL TRANSISTOR TRANSISTOR		
07 -18 019 0301 0302			DTC143EK DTC144EK DTC114EK 2SA1182(Y)	DIGITAL TRANSISTOR DIGITAL TRANSISTOR DIGITAL TRANSISTOR TRANSISTOR		
Z1		*	X59-3940-01	MODULE UNIT		
	1			METER (X59-3940-01)	<u>,</u>	
C1 ,2			CK73FB1E103K E23-0471-05	CHIP C 0.01UF K TERMINAL		
R1 R2 R3 R4 ,5 R6			RK73FB2A103J RK73FB2A684J RK73FB2A684J RK73FB2A224J RK73FB2A104J RK73FB2A102J	CHIP R 10K J 1/10W   CHIP R 680K J 1/10W   CHIP R 220K J 1/10W   CHIP R 100K J 1/10W   CHIP R 100K J 1/10W   CHIP R 1.0K J 1/10W		
<b>R7</b> R8 R9 R10 R11			RK73FB2A103J RK73FB2A224J RK73FB2A684J RK73FB2A104J RK73FB2A224J	CHIP R 10K J 1/10W   CHIP R 220K J 1/10W   CHIP R 680K J 1/10W   CHIP R 100K J 1/10W   CHIP R 220K J 1/10W   CHIP R 100K J 1/10W   CHIP R 220K J 1/10W		
R12 R13,14			RK7 <b>3FB2A</b> 102J R92 <b>-067</b> 0-05	CHIPR 1.0K J 1/10W CHIPR 0 OHM		
D1 ,2 IC1			HSM88AS LM2904M	IC (or NJM2904M)		

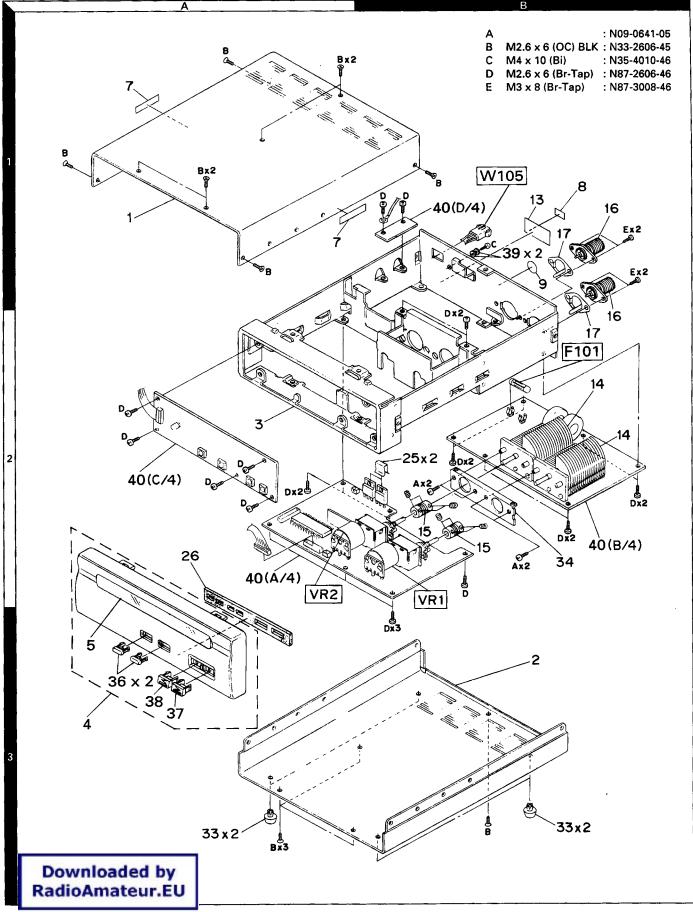
L:Scandinavia Y:PX(Far East, Hawaii)

Y:AAFES(Europe)

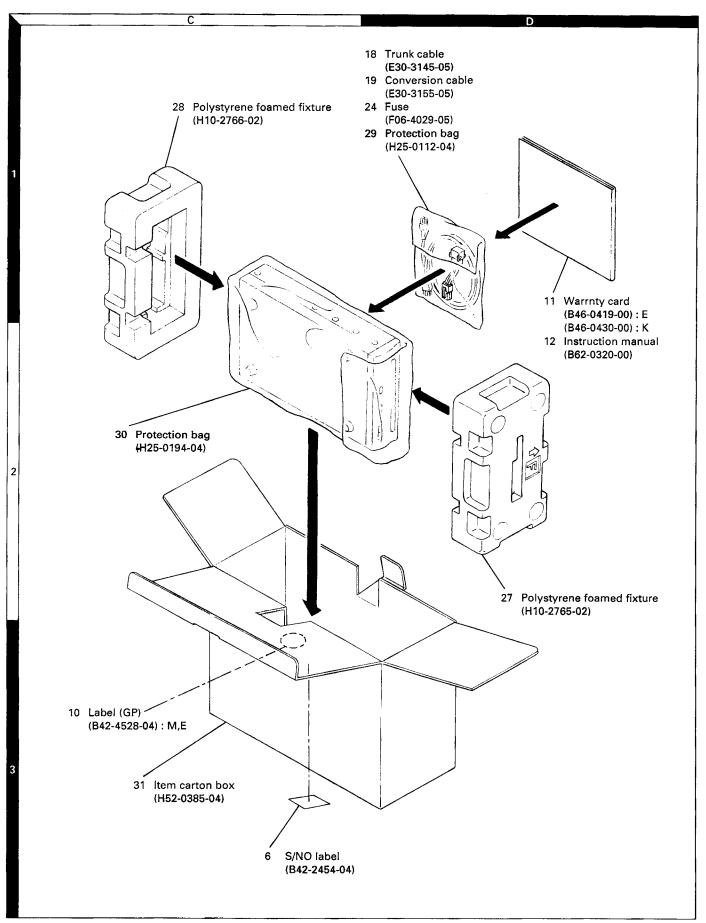
P:Canada T:England E:Europe M:Other Areas

X:Australia

## **EXPRODED VIEW**



## PACKING



## **DISASSEMBLY FOR REPAIR**

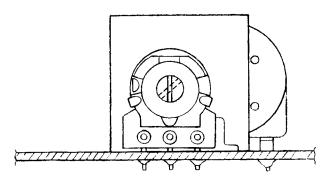
### Variable condenser adjustment method

If the motor-driver variable resistor is replaced

The motor-driver variable resistor has a slit in the shaft, and is set to the position shown Figure 1 at the factory.

To adjust the position, connect the variable condenser to the motor-driver variable resistor with the rotor plates of the variable condenser set upright.

Turn the rotor plates counterclockwise 90 degrees as shown in Figure 3. Never turn the rotor plates clockwise, otherwise tuning cannot be performed correctly.



#### Fig. 1 Motor-driver variable resistor

#### If the motor-driver variable resistor is not replaced

If the AT-50 is reset (see page 18 for the method of resetting), the motor-driver variable resistor is initialized to the 14MHz-band position. The slit position is about 15° clockwise (the dotted line in Figure 1).

Set the blades of the variable condenser to about 105° (the dotted line in Figure 3), and couple it with the motor-driver variable resistor.

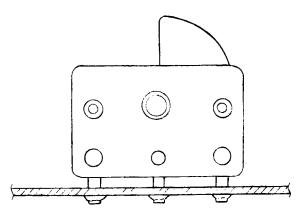


Fig. 2 Variable condenser

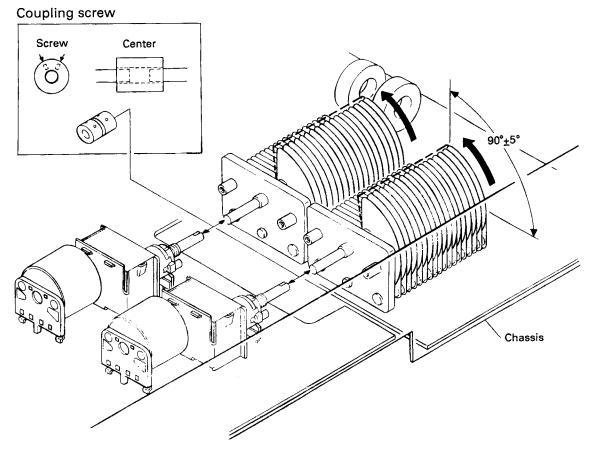


Fig. 3 Initial setting

## **ADJUSTMENT**

### **Required test equipment**

### 1. DC voltmeter (DVM)

1) Input resistance : More than  $1M\Omega$ 

2) Voltage range : 1.5 to 1000V AC / DC

Note : A high-precision multimeter may be used. However, accurate readings can not be obtained for high-impedance circuits.

#### 2. Power meter

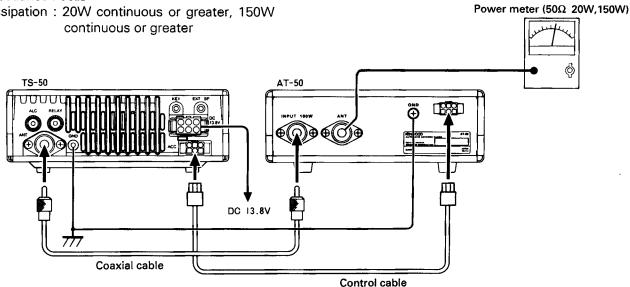
- 1) Frequency limits : 30MHz or greater
- 2) Impedance :  $50\Omega$
- 3) Dissipation : 20W continuous or greater, 150W continuous or greater

### 3. RF Dummy Load

- 1) Impedance :  $20\Omega$ ,  $150\Omega$
- 2) Dissipation : 150W or greater
- Note : The length of both the  $150\Omega$  and  $20\Omega$  dummy load cables must be 10cm or less.

### 4. DC Power Supply

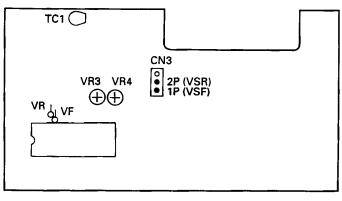
1) DC 13.8V



AT unit (B/4)

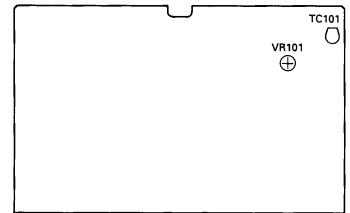
### **Adjustment Point**

AT unit (A/4)



- TC1: 18, 28MHz band phase
- VR3 : Power meter

VR4 : SWR meter



TC101 : Null VR101 : Detection circuit frequency characteristics

## **ADJUSTMENT**

	Condition	Measurement		Adjustment		ustment	0	
item		Test- equipment	Unit	Terminal	Unit	Parts	Method	Specifications/Remarks
1. Null adjustment	1) AT-50 AUTO/THRU : THRU TS-50 Frequency : 1.91MHz MODE : CW 10W transmission	DC V.M Power meter	AT	CN3-2 pin (VSR)	AT	TC101	Minimize the voltage by turning TC101.	Reference value : 50mV or less
2. Detection circuit frequency characteristics adjustment	1) AT-50 AUTO/THRU : THRU TS-50 Frequency : 1.91MHz MODE : CW 10W transmission			CN3-1 pin (VSF)			Measure the voltage.	2.5V~3.5V
	2) AT-50 AUTO/THRU : THRU TS-50 Frequency : 29.0MHz MODE : CW 10W transmission				AT	VR101	Set the voltage to the same level as for 1.91MHz by turning VR101.	
3. Power meter adjustment	1) AT-50 AUTO/THRU : THRU TS-50 Frequency : 14.0MHz MODE : CW 10W transmission			IC11- 56 pin (VF)		VR3	Set the voltage to 0.9V by turning VR3.	±0.02V
4. SWR meter adjustment	1) AT-50 AUTO/THRU : THRU TS-50 Frequency : 1.91MHz MODE : CW 100W (When terminated with 50Ω) Dummy						Measure the VF voltage.	
	Terminate with 150Ω Transmission 2) Same as 1)			IC11- 57 pin (VR)	AT	VR4	Turn VR4 so that the voltage is twice as large as the VF measured in 1). (VR = VF x 2)	
5. Confirmation of automatic tuning mode	AT TUNE : ON Transmit in all bands with each dummy. 20Ω dummy 150Ω dummy 50Ω power meter	[ =, [	Rear panel	ANT			Check	Tuning must be performed correctly.
					AT	TC1	capacitor vibrates slig band tuning, adjust T	stable and the variable htly during the 18, 28MHz 1 so that the variable VR must be 1.2 or less.}
6. Reset	1) TS-50 POWER SW : OFF AT-50 Hold down the BAND < and > keys, TS-50 POWER SW : ON						Check	The BAND LED blinks.
	2) TS-50 POWER SW : OFF					l		

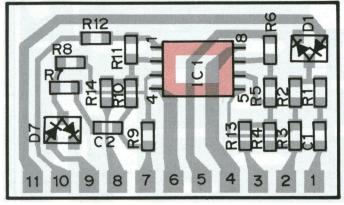
## **TERMINAL FUNCTION**

Connector No.	Terminal No.	Terminal Name	Terminal Function	
AT UNIT (X53-3470-00)				
CN1	Coaxial	AT2	AT output.	
CN2	Coaxial	AT1	AT input.	
CN3	1	VSF	Forward wave detection voltage input.	
	2	VSR	Reflected wave detection voltage input.	
	3	GND	GND.	
CN4	1	TT	Serial output.	
	2	TS	Serial control input.	
	3	10A	AT coil tap band data, 7.5 to 10.5MHz.	
	4	14A	AT coil tap band data, 10.5 to 14.5MHz.	
	5	18A	AT coil tap band data, 14.5 to 21.5MHz.	
	6	25A	AT coil tap band data, 21.5 to 25.0MHz.	
	7	28A	AT coil tap band data, 25.0 to 30.0MHz.	
	8	ATA	THRU/ON switching signal. On: Low	
	9	4A	AT coil tap band data, 2.0 to 4.0MHz.	
_	10	7A	AT coil tap band data, 4.0 to 7.5MHz.	
CN5	1	5V	5V.	
	2	SAT	AUTO/THRU key switch input.	
	3	STN	TUNE key switch input.	
	4	SDN	DOWN key switch input.	
	5	SUP	UP key switch input.	
	6	LCK	LED driver serial clock.	
	7	LDA	LED driver serial data.	
	8	LBL	LED driver light control output.	
	9	LEN	LED driver enable.	
	10	GND	GND.	
_	11	NC	Not used.	
CN6	1	NMI	Power supply voltage drop interrupt input.	
	2	8V	8V	
CN7	1	14S	14V.	
	2	GND	GND.	
CN101	Coaxial		AT output.	
CN102	Coaxial	—	AT input.	

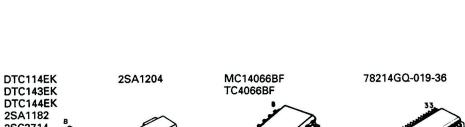
Connector No.	Terminal No.	Terminal Name	Terminal Function
CN103	1	VSF	Forward wave detection voltage output.
	2	VSR	Reflected wave detection voltage output.
	3	GND	GND.
CN104	1	14S	14V.
	2	GND	GND.
	3	Π	Serial uotput.
	4	TS	Serial control input.
	5	10A	AT coil tap band data, 7.5 to 10.5MHz.
	6	14A	AT coil tap band data, 10.5 to 14.5MHz.
	7	18A	AT coil tap band data, 14.5 to 21.5MHz.
	8	25A	AT coil tap band data, 21.5 to 25.0MHz.
	9	28A	AT coil tap band data, 25.0 to 30.0MHz.
	10	ATA	THRU/ON switching signal. On : Low
	11	4A	AT coil tap band data, 2.0 to 4.0MHz.
	12	7A	AT coil tap band data, 4.0 to 7.5MHz.
CN105		14S	Overvoltage protection circuit 13.8V input.
W22	1	NMI	Power supply voltage drop interrupt input.
1	2	8V	8V.
W105	1	14S	14V.
	2	ATG	GND.
	3	Π	Serial output.
	4	TS	Serial control input.
W201	1	GND	GND.
	2	LEN	LED driver enable.
	3	LBL	LED driver light control output.
	4	LDA	LED driver serial data.
	5	LCK	LED driver serial clock.
	6	SUP	UP key switch input.
	7	SDN	DOWN key switch input.
	8	STN	TUNE key switch input.
	9	SAT	AUTO/THRU key switch input.
	10	5V	5V
W301		14S	Overvoltage protection circuit 13.8V input.

PC BOARD VIEWS AT-50

**METER (X59-3940-01) Component side view** 



В











С



NJM2902M



TC4S584F

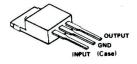
Ε

2

4

6

μPC7805H µPC7808H

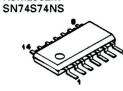




M51951BML

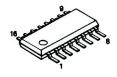


BA6109U2





µPD6345GS

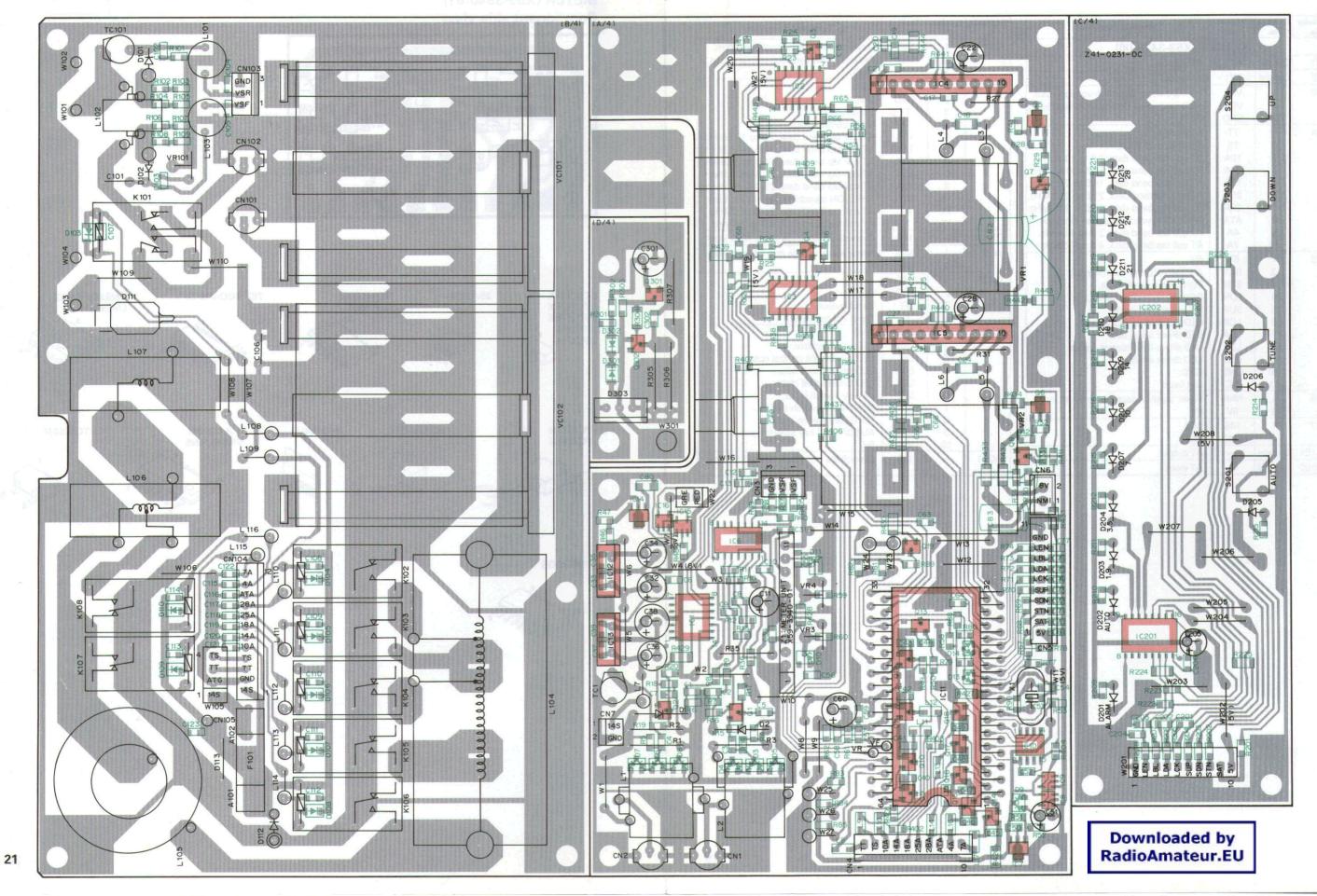


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# AT-50 PC BOARD VIEWS

AT UNIT (X53-3470-00) Component side view

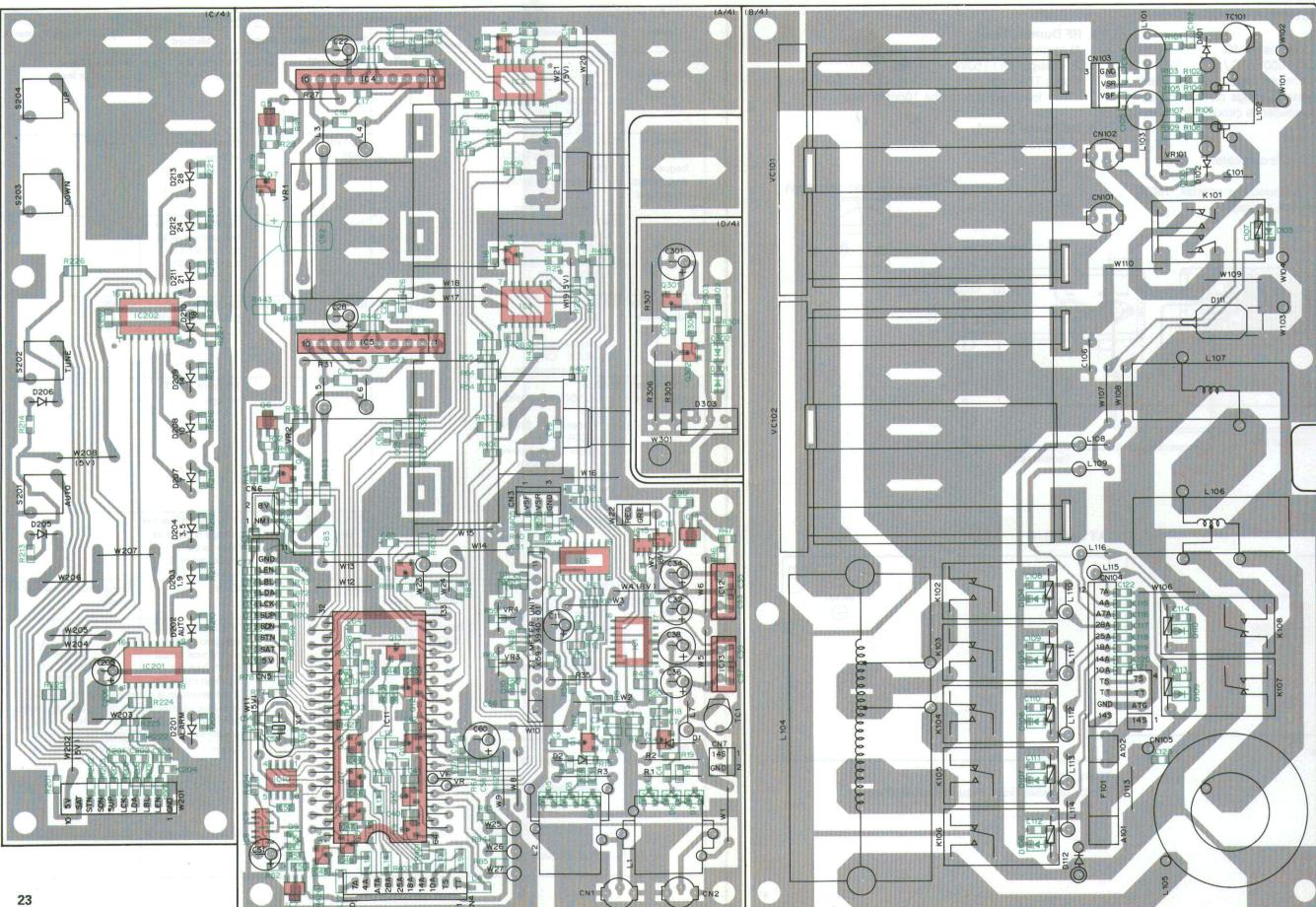
terminal function



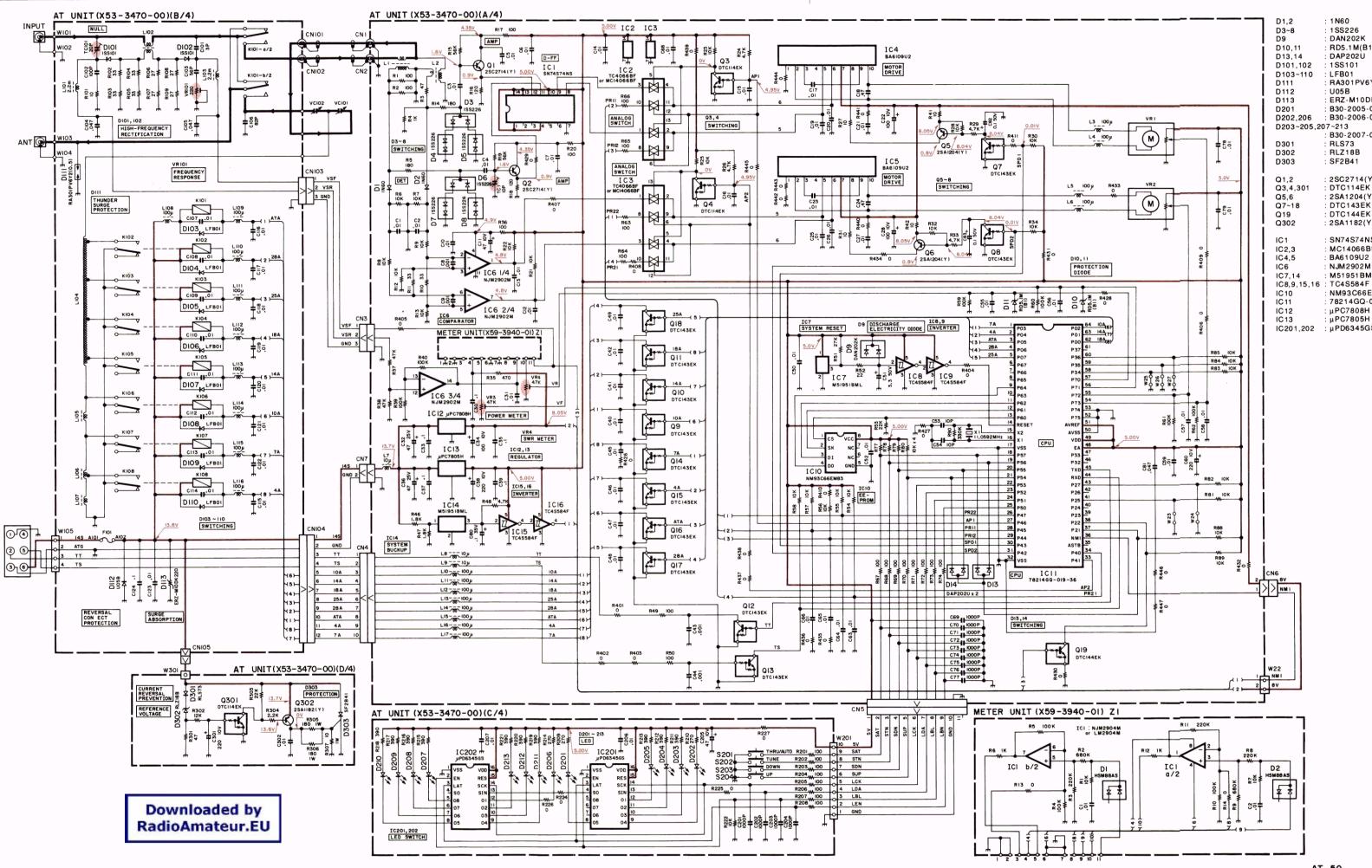
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### AT UNIT (X53-3470-00) Foil side view



### Above diagram is numbered pages 23 and 24 by Kenwood. This is a placeholder to keep page numbering correct in Adobe.



schematic diagram AT-50

1N60

1SS226

DAN202K

DAP202U

1SS101

U05B

RD5.1M(B1)

: LFB01 : RA301PV6Y2(0.5)

ERZ-M10DK220

B30-2005-05

: B30-2006-05

: B30-2007-05

2SC2714(Y)

2SA1204(Y)

DTC143EK

: DTC144EK

: 2SA1182(Y)

SN74S74NS

BA6109U2

NJM2902M

M51951BML

: 1C45554F : NM93C66EM83 : 78214GQ-019-36 : μPC7808H : μPC7805H : μPD6345GS

MC14066BF or TC4066BF

DTC114EK

: RLS73 : RLZ18B

: SF2B41

### Above schematic is numbered pages 25, 26 and 27 by Kenwood.

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### Above schematic is numbered pages 25, 26 and 27 by Kenwood.

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## PG-4M (CONTROL CABLE)

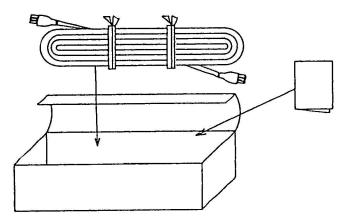
### PG-4M External View



PG-4M	Wiring

Pin No.	Wiring color	Function
1	Shield (Black)	GND
2	Violet	TT
3	Black	GND
4	_	_
5	Blue	TS
6	Red	14S

### PG-4M Packing



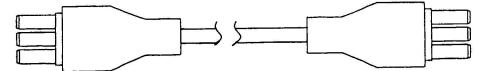
### PG-4M Parts List

Ref.No.	New	Parts No.	Description
	×	E30-3158-05	Control cable

### PG-4M Dimension/Weight

Dimension	6m
Weight	400g

### PG-4M Outside View



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## **SPECIFICATIONS**

Frequency range	
Voltage required	
Ground system	. Negative ground
Current consumed	. 2A or less
Power limit (maximum throughput)	. 100W continuous wave (after tuning)
Operating temperature range	. —20°C ~ +60°C
Input impedance	. 50 $\Omega$ unbalanced
Maximum VSWR (after tuning)	. 1.3 or less
Tuning power	. 6 ~ 20W
Antenna impedance range	. 20 to 150 $\Omega$ (SWR : approx. 2.5 or less)
Tuning time	. Initial tuning time : 30 seconds or less
-	After first preset : 3 seconds or less
Dimensions [W x H x D]	. 180 x 60 (68.5) x 233 (247) mm
(Including projections)	
Weight	. 2.1kg
•	

Note : Ratings are subject to change due to technological improvement.

## **KENWOOD CORPORATION**

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